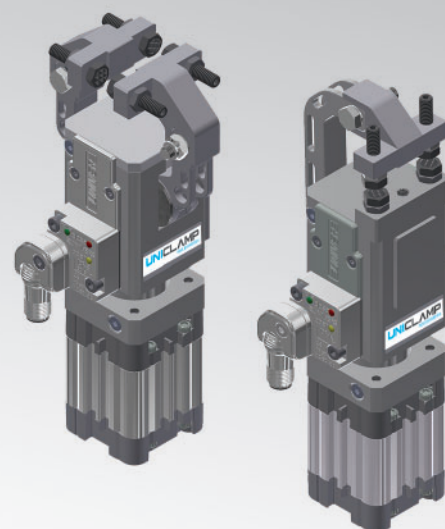


UGPS

Gripper pneumatico **UNICLAMP**



U	G	P	S	3	2	D	1	A	K	R	3	0
1	2	3	4	5	6	7	8	9				

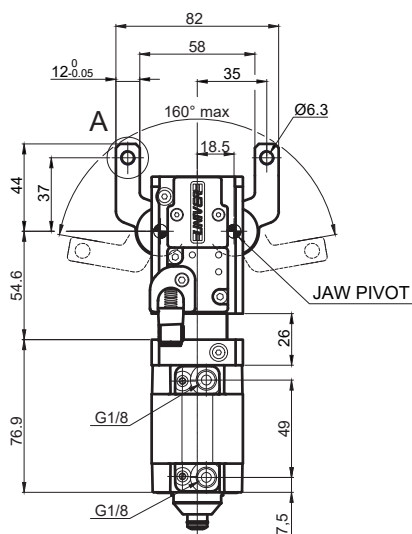
1 Serie	2 Materiale bracci	3 Taglia cilindro
UGP = Gripper pneumatico UNICLAMP , angolo regolabile	S = Acciaio (standard)	32 = 32 mm 40 = 40 mm

4 Bracci	5 Dita	6 Sensore
S0 = Singolo braccio, senza terminali S1 = Singolo braccio, terminali predisposti per 1 paio di dita S2 = Singolo braccio, terminali predisposti per 2 paia di dita D0 = Doppio braccio, senza terminali D1 = Doppio braccio, terminali predisposti per 1 paio di dita D2 = Doppio braccio, terminali predisposti per 2 paia di dita	0 = No dita A = Dita zigrinate B = Dita zigrinate orientabili C = Dita piatte D = Dita concave-convexe (1+1) E = Dita piatte orientabili	N = Senza sensore (con piastra di chiusura) K = Sensore elettronico PNP (ottico) (DF-K) D = Sensore pneumatico J = Sensore elettronico NPN (ottico) (DF-J) Y = Sensore elettronico PNP (ottico) (DF-Y) led bianco

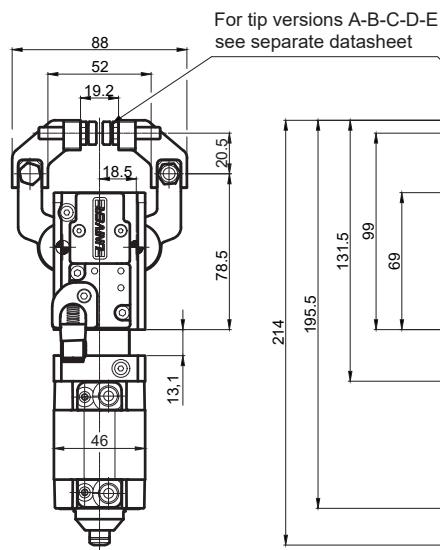
7 Lato montaggio sensore	8 Fissaggio
N = Senza sensore R = Destro (lato alimentazione) L = Sinistro	0 = Senza fissaggio 1 = Fissaggio a fl angia (Ø32 LGP32MP, Ø40 LGP40MP) 2 = Fissaggio orbitale rotazione 360°, Ø25 (Ø32 LGP32MO25, Ø40 LGP40MO25) 3 = Fissaggio orbitale rotazione 360°, Ø30 (Ø32 LGP32MO30, Ø40 LGP40MO30) 4 = Fissaggio orbitale rotazione 360°, Ø40 (Ø40 LGP40MO40) 5 = Fissaggio orbitale rotazione 360°, Ø45 (Ø40 LGP40MO45) 6 = Fissaggio posteriore (Ø32 LGP32PT070, Ø40 LGP40PT080) 7 = Fissaggio posteriore largo (Ø40 LGP40PT110)

9 Revisione prodotto
Assegnato da UNIVER

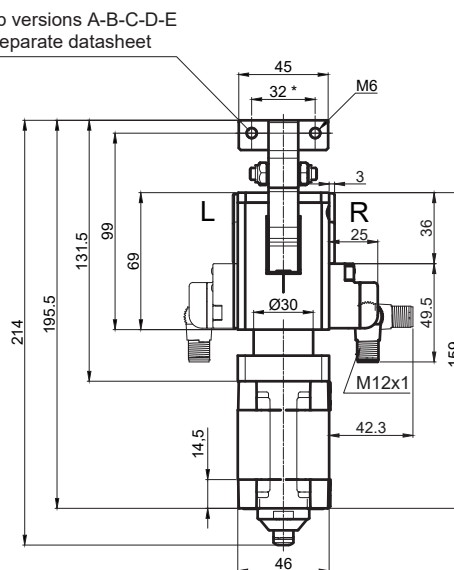
UGPS32D__K_10



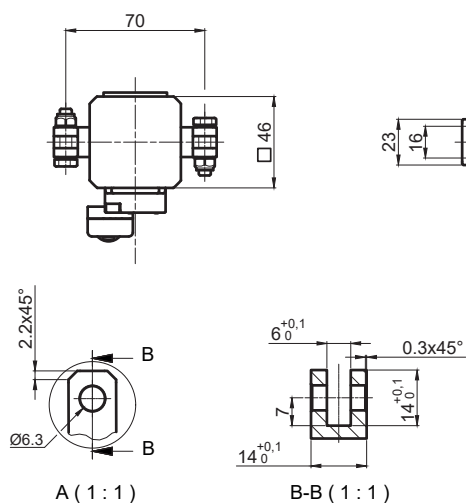
UGPS32D00K_0



UGPS32D1_K_0

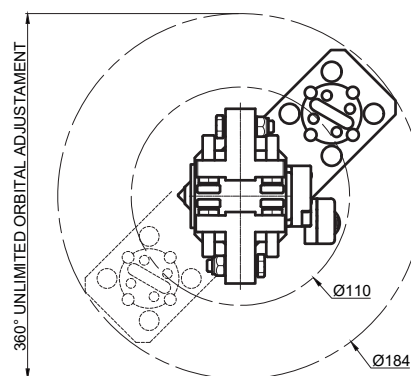


UGPS32D2_K_0

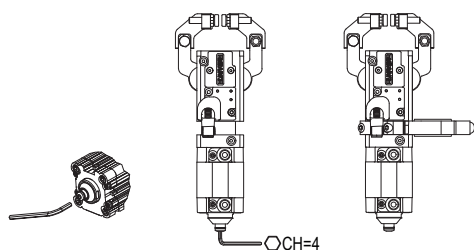


A (1 : 1)

B-B (1 : 1)



UGPS32D2_K_1



LGP32MP

Bore Ø	Holding moment	Clamping force at 5 bar	Weight	Mount weight
32 mm	150 Nm	350 N	1 Kg	0,16 Kg

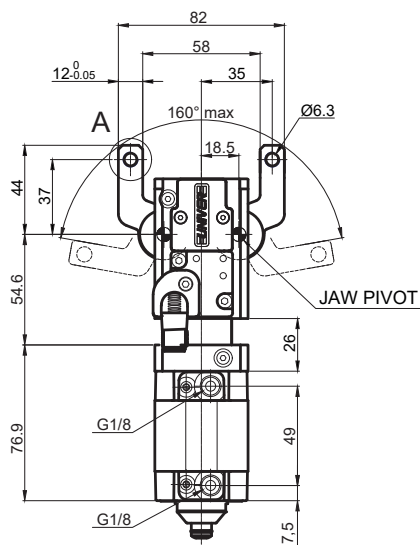
Min./Max. operating pressure: **0,4 / 0,6 MPa**
 Operating temperature: **5°÷ 45° C**
 Opening angle: **adjustable from 10° to 50°**
 Electronic sensor with M12 swivel connector, from 0° to 90°, in steps of 10°
 Supply voltage: 10 ÷ 30 Vdc
 IP code: **IP 65**

*: TOLERANCE BETWEEN DOWELS ± 0,02, BETWEEN SCREW HOLES ± 0,1

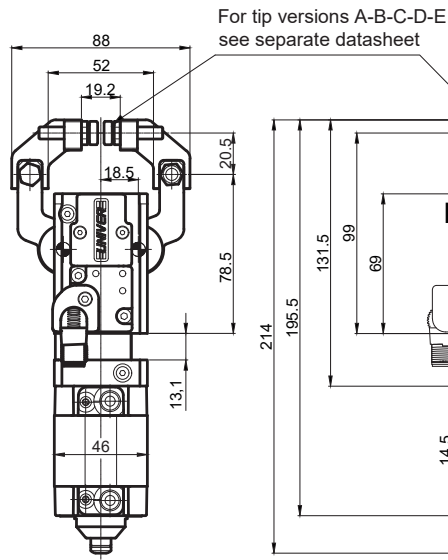
Subject to technical modifications without notice

Rev. 00 23.09.19

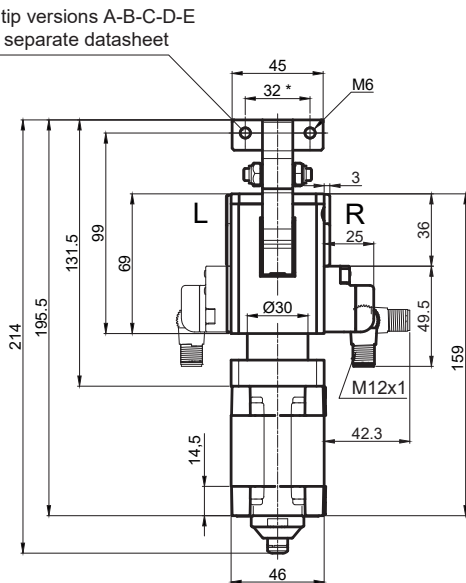
UGPS32D__K_20



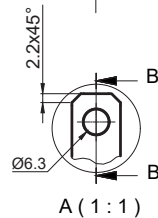
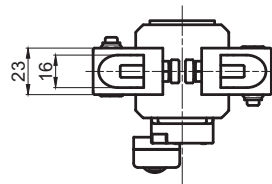
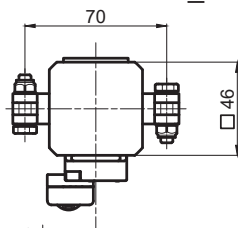
UGPS32D00K_0



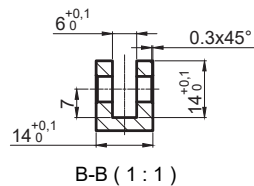
UGPS32D1_K_0



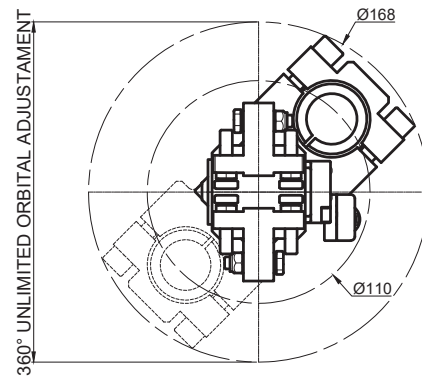
UGPS32D2_K_0



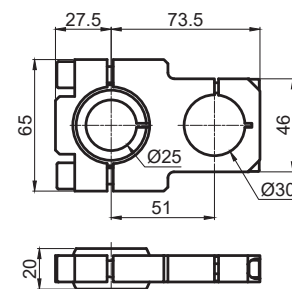
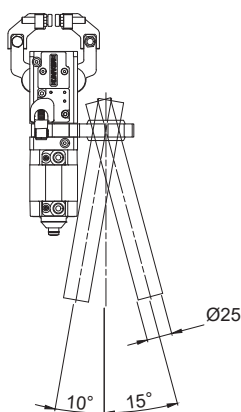
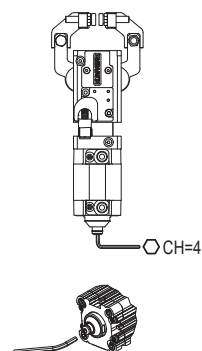
A (1 : 1)



B-B (1 : 1)



UGPS32D2_K_2



LGP32MO25

Bore Ø	Holding moment	Clamping force at 5 bar	Weight	Mount weight
32 mm	150 Nm	350 N	1 Kg	0,19 Kg

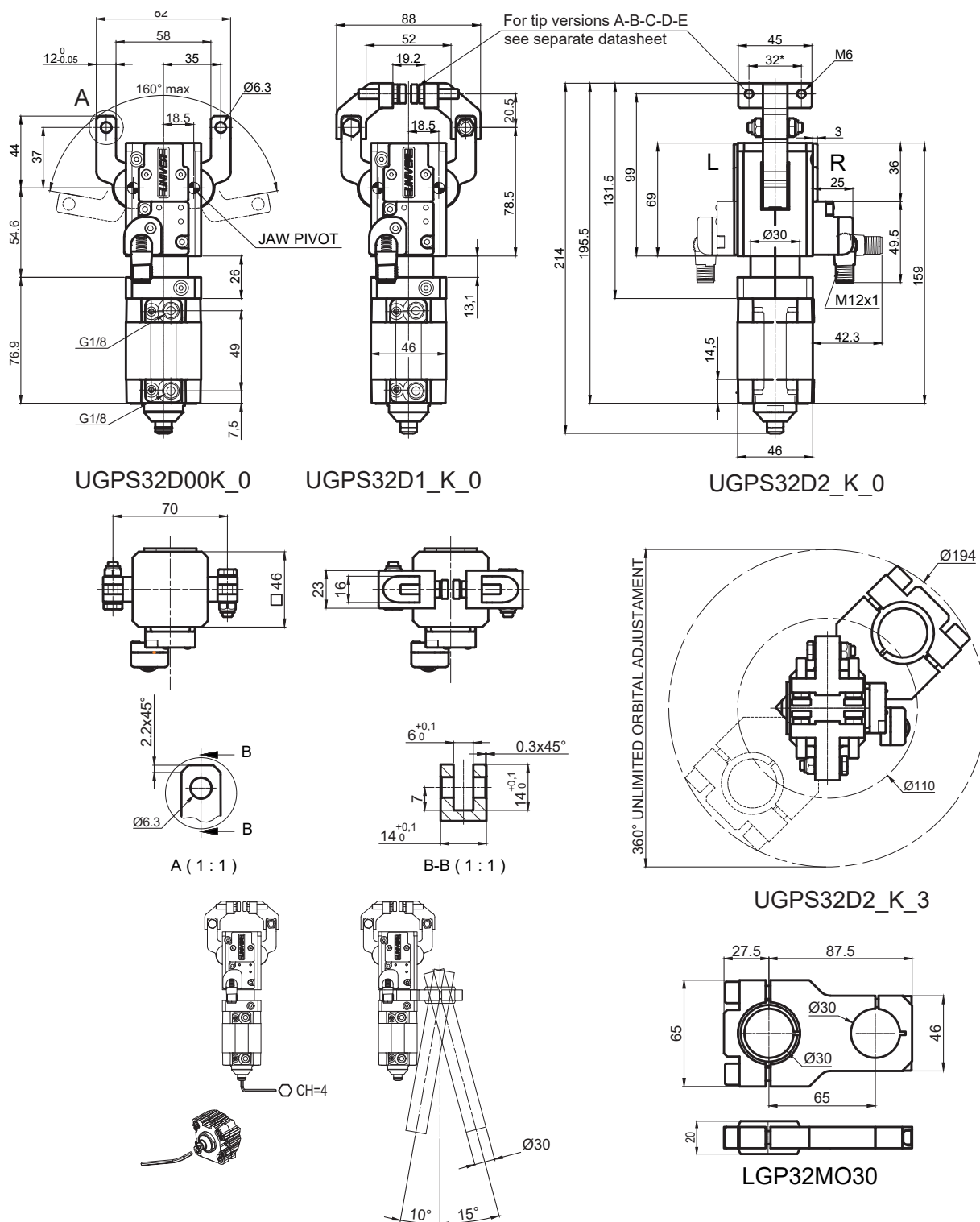
*: TOLERANCE BETWEEN DOWELS $\pm 0,02$, BETWEEN SCREW HOLES $\pm 0,1$

Min./Max. operating pressure: **0,4 / 0,6 MPa**
Operating temperature: **5° ÷ 45° C**
Opening angle: **adjustable from 10° to 50°**
Electronic sensor with M12 swivel connector, from 0° to 90°, in steps of 10°
Supply voltage: 10 ÷ 30 Vdc
IP code: **IP 65**

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UGPS32D__K_30



Bore Ø	Holding moment	Clamping force at 5 bar	Weight	Mount weight
32 mm	150 Nm	350 N	1 Kg	0,2 Kg

*: TOLERANCE BETWEEN DOWELS $\pm 0,02$, BETWEEN SCREW HOLES $\pm 0,1$

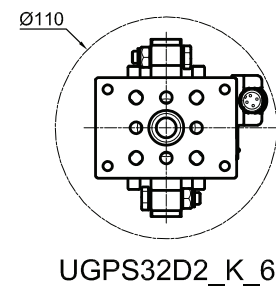
Min./Max. operating pressure: **0,4 / 0,6 MPa**
 Operating temperature: **5° ÷ 45° C**
 Opening angle: **adjustable from 10° to 50°**
 Electronic sensor with M12 swivel connector, from 0° to 90°, in steps of 10°
 Supply voltage: 10 ÷ 30 Vdc
 IP code: **IP 65**

Subject to technical modifications without notice

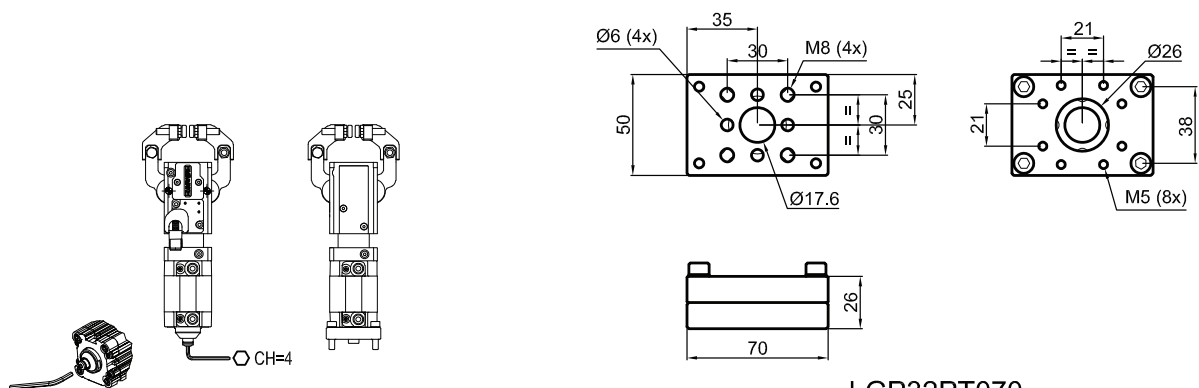
Rev. 00 23.09.19

[illegible]

UGPS32D2_K_0



UGPS32D2_K_6



LGP32PT070

Min./Max. operating pressure: **0,4 / 0,6 MPa**
 Operating temperature: **5° + 45° C**
 Opening angle: **adjustable from 10° to 50°**
 Electronic sensor with M12 swivel connector than can be
 orientated at 0° or 90°
 Supply voltage: 10 ÷ 30 Vdc
 IP code: **IP 65**

Rev. 00 24.03.20